



On strategic stability in discontinuous games

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ABSTRACT

We identify a class of discontinuous normal-form games whose members possess strategically stable sets, defined according to an infinite-game extension of Kohlberg and Mertens's (1986) equilibrium concept, and show that, generically, a set is stable if and only if it contains a single Nash equilibrium.

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1. Introduction

There are several refinements of the Nash equilibrium concept for normal-form games with finite action spaces. Some authors have studied extensions of the standard refinements to normal-form games with infinitely many strategies (e.g., perfect equilibrium (Simon and Stinchcombe, 1995; Carbonell-Nicolau, forthcoming-a-b, 2011), strategic stability (Al-Najjar, 1995), and essential stability (e.g., Yu, 1999; Zhou et al., 2007; Carbonell-Nicolau, 2010a)).

This paper examines an infinite-game generalization of Kohlberg and Mertens's (1986) strategic stability. For this notion, Al-Najjar (1995) shows that metric, compact, and continuous games possess stable sets of mixed strategies. In this paper, we extend this existence result to a class of possibly discontinuous games with the property that for generic members of this class, stable sets reduce to equilibrium points.

2. Preliminaries

A **normal-form game** is a collection $G = (X_i, u_i)_{i=1}^N$, where N is a finite number of players, X_i is a nonempty action space for player i , and $u_i : X \rightarrow \mathbb{R}$, a bounded and Borel measurable map with domain $X := \times_{i=1}^N X_i$, represents player i 's payoff function. When X_i

is compact and metric for each $i \in \{1, \dots, N\}$, G is called a **compact metric game**.

The **mixed extension** of a compact metric game G is the game

$$\bar{G} = (M_i, U_i)_{i=1}^N,$$

where, for each i , M_i represents the set of Borel probability measures on X_i , endowed with the weak* topology, and $U_i : M \rightarrow \mathbb{R}$ is defined by

$$U_i(\mu) := \int_X u_i d\mu,$$

where $M := \times_{i=1}^N M_i$.

Given a compact, metric game $G = (X_i, u_i)_{i=1}^N$, the set M , together with the Prokhorov metric on M , can be viewed as a metric space.¹ The Prokhorov metric on M , $\varrho : M^2 \rightarrow \mathbb{R}$, is defined as

$$\varrho(\mu, \nu) := \inf\{\varepsilon > 0 : \mu(B) \leq \nu(B^\varepsilon) + \varepsilon \text{ and } \nu(B) \leq \mu(B^\varepsilon) + \varepsilon, \text{ for all } B\},$$

where

$$B^\varepsilon := \{x \in X : d(x, y) < \varepsilon \text{ for some } y \in B\},$$

and d denotes the metric associated with X .

A measure μ_i in M_i is said to be **strictly positive** if $\mu_i(O) > 0$ for every nonempty open subset O of X_i .

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¹ For compact metric games, the weak* topology on M coincides with the topology induced by the Prokhorov metric on M .

For each i , let \widehat{M}_i be the set of all strictly positive members of M_i , and define $\widehat{M} := \times_{i=1}^N \widehat{M}_i$. For $v = (v_1, \dots, v_N) \in \widehat{M}$ and $\delta = (\delta_1, \dots, \delta_N) \in [0, 1]^N$, define

$$M_i(\delta_i v_i) := \{\mu_i \in M_i : \mu_i \geq \delta_i v_i\}$$

and $M(\delta v) := \times_{i=1}^N M_i(\delta_i v_i)$. The game

$$\overline{G}_{\delta v} = (M_i(\delta_i v_i), U_i|_{M(\delta v)})_{i=1}^N$$

is called a **Selten perturbation** of G . When $\delta_1 = \dots = \delta_N$, we slightly abuse notation and write $\overline{G}_{\delta v}$ with $\delta = \delta_1 = \dots = \delta_N$.

The graph of G is the set

$$\Gamma_G := \{(x, \alpha) \in X \times \mathbb{R}^N : u_i(x) = \alpha_i, \text{ for all } i\}.$$

The closure of Γ_G is denoted by $\overline{\Gamma}_G$.

Definition 1. Given a game $G = (X_i, u_i)_{i=1}^N$, a strategy profile $x = (x_1, \dots, x_N) \in X$ is a **Nash equilibrium** of G if for each i , $u_i(x) \geq u_i(y_i, x_{-i})$ for every $y_i \in X_i$.

Given a game $G = (X_i, u_i)_{i=1}^N$, a Nash equilibrium of the mixed extension \overline{G} is called a **mixed-strategy Nash equilibrium** of G . By a slight abuse of terminology, we sometimes refer to a mixed-strategy Nash equilibrium of G simply as a Nash equilibrium of G .

Definition 2. A mixed-strategy profile $\mu \in M$ is a **trembling-hand perfect (thp) equilibrium** of $G = (X_i, u_i)_{i=1}^N$ if there are sequences (δ^n) , (v^n) , and (μ^n) such that $(0, 1)^N \ni \delta^n \rightarrow 0$ and $v^n \in \widehat{M}$ for each n , $\mu^n \rightarrow \mu$, and each μ^n is a Nash equilibrium of the perturbed game $\overline{G}_{\delta^n v^n}$.

Alternative definitions of trembling-hand perfection that are equivalent to Definition 2 can be found in Carbonell-Nicolau (forthcoming-b).

For $\emptyset \neq E \subseteq M$ and $\mu \in M$, define

$$\varrho(\mu, E) := \inf\{\varrho(\mu, v) : v \in E\}.$$

For $\varepsilon > 0$ and $\emptyset \neq E \subseteq M$, a profile $\mu \in M$ is said to be **ε -close to E** if $\varrho(\mu, E) < \varepsilon$.

Given a game $G = (X_i, u_i)_{i=1}^N$, let \mathcal{E}_G be the family of all nonempty closed sets E of Nash equilibria of \overline{G} with the following property: for each $\varepsilon > 0$ there exists $\alpha \in (0, 1]$ such that for each $\delta \in (0, \alpha)^N$ and every $v \in \widehat{M}$, the perturbed game $\overline{G}_{\delta v}$ has a Nash equilibrium ε -close to E .

Definition 3. A set of mixed-strategy profiles in M is a **stable set** of $G = (X_i, u_i)_{i=1}^N$ if it is a minimal element of the set \mathcal{E}_G ordered by set inclusion.

3. Existence of stable sets

We adapt ideas from Carbonell-Nicolau (forthcoming-a), Carbonell-Nicolau (2011), and Carbonell-Nicolau (2010a) to derive the main results. Some arguments are omitted in the interest of brevity. The reader is referred to the working paper version, Carbonell-Nicolau (2010b), of the current manuscript for details.

The following definitions are taken from Reny (1999).

Definition 4. The game $G = (X_i, u_i)_{i=1}^N$ is **better-reply secure** if for every $(x, \alpha) \in \overline{\Gamma}_G$ such that x is not a Nash equilibrium of G , there exist $i, y_i \in X_i$, a neighborhood $O_{x_{-i}}$ of x_{-i} , and $\beta \in \mathbb{R}$ such that $u_i(y_i, y_{-i}) \geq \beta > \alpha_i$ for all $y_{-i} \in O_{x_{-i}}$.

Definition 5. The game $G = (X_i, u_i)_{i=1}^N$ is **payoff secure** if for each $\varepsilon > 0, x = (x_1, \dots, x_N) \in X$, and i , there exist $y_i \in X_i$ and a neighborhood $O_{x_{-i}}$ of x_{-i} such that $u_i(y_i, y_{-i}) > u_i(x) - \varepsilon$ for all $y_{-i} \in O_{x_{-i}}$.

The existence of stable sets in a game $G = (X_i, u_i)_{i=1}^N$ crucially relies on the existence of Nash equilibria in neighboring Selten perturbations of G .

Lemma 1. Suppose that G is a compact, metric game. If \overline{G} is better-reply secure and there exists $\alpha \in (0, 1)$ such that $\overline{G}_{\delta \mu}$ has a Nash equilibrium for every $(\delta, \mu) \in (0, \alpha] \times \widehat{M}$, then G possesses a stable set, and all stable sets of G contain only trembling-hand perfect equilibria, which are also Nash.

Proof. The set of Nash equilibria in \overline{G} belongs to \mathcal{E}_G . The set of Nash equilibria in \overline{G} is nonempty and closed because \overline{G} is compact, metric, and better-reply secure (Reny, 1999, Corollary 5.2 and Remark 3.1). The proof that for each $\varepsilon > 0$ there exists $\alpha \in (0, 1]$ such that for each $\delta \in (0, \alpha)^N$ and every $v \in \widehat{M}$, $\overline{G}_{\delta v}$ has a Nash equilibrium ε -close to the set of Nash equilibria in \overline{G} is similar to the proof of Proposition 1 in Carbonell-Nicolau (forthcoming-a). We omit the details.

Next, every decreasing chain (E^α) in \mathcal{E}_G (ordered by set inclusion) has a lower bound. In fact, $\bigcap_\alpha E^\alpha$ is a lower bound for (E^α) . To see this, note first that the collection (E^α) has the finite intersection property, and therefore, since M is compact, $\bigcap_\alpha E^\alpha \neq \emptyset$. The set $\bigcap_\alpha E^\alpha$ is clearly a lower bound for (E^α) if $\bigcap_\alpha E^\alpha$ is a member of (E^α) . We assume that $\bigcap_\alpha E^\alpha$ is a not member of (E^α) and derive a contradiction. Suppose that $\bigcap_\alpha E^\alpha$ is a not member of (E^α) . Then, since $\bigcap_\alpha E^\alpha \neq \emptyset$, there exists $\varepsilon > 0$ such that for every $\alpha > 0$, there exist $\delta \in (0, \alpha)^N$ and $v \in \widehat{M}$ such that no Nash equilibrium of $\overline{G}_{\delta v}$ is ε -close to $\bigcap_\alpha E^\alpha$. Then, since each E^α is a member of \mathcal{E}_G , the Hausdorff distance (with respect to the Prokhorov metric) between $\bigcap_\alpha E^\alpha$ and E^β is bounded away from zero for every β (otherwise, for some β , the Hausdorff distance between E^β and $\bigcap_\alpha E^\alpha$ would lie below $\frac{\varepsilon}{2}$, and there would exist some $\alpha^* \in (0, 1]$ such that, for each $\delta \in (0, \alpha^*)^N$ and every $v \in \widehat{M}$, some Nash equilibrium of $\overline{G}_{\delta v}$ would be $\frac{\varepsilon}{2}$ -close to E^β , and therefore ε -close to $\bigcap_\alpha E^\alpha$). Because (E^α) is a totally ordered subset of \mathcal{E}_G (and hence a directed set), the map $\zeta : (E^\alpha) \rightarrow (E^\alpha)$ defined by $\zeta(E^\alpha) := E^\alpha$ is a net in \mathcal{E}_G . But since ζ is a net of nonempty, closed subsets of the compact set M , and since the hyperspace of nonempty compact subsets of M is a compact, metric space relative to the Hausdorff metric, there is a subnet of ζ , which we denote again by ζ , that (Hausdorff) converges to some nonempty compact subset E of M . Hence, because $E = \bigcap_\alpha E^\alpha$, we see that ζ (Hausdorff) converges to $E = \bigcap_\alpha E^\alpha$, which contradicts the fact that the Hausdorff distance between $\bigcap_\alpha E^\alpha$ and E^β is bounded away from zero for every β .

To see that $E = \bigcap_\alpha E^\alpha$, suppose first that there exists $\mu \in E \setminus (\bigcap_\alpha E^\alpha)$. Then there exists α such that $\mu \in E \setminus E^\alpha$. But $E \subseteq E^\alpha$, a contradiction. To see that $E \subseteq E^\alpha$, note that since E^α is closed, $v \in E \setminus E^\alpha$ implies that $\inf\{\varrho(v, p) : p \in E^\alpha\} > 0$, so (given $v \in E$) the Hausdorff distance between E and E^α is greater than or equal to $\inf\{\varrho(v, p) : p \in E^\alpha\}$. Hence, for all $E^\beta \subseteq E^\alpha$, the Hausdorff distance between E and E^β is greater than or equal to $\inf\{\varrho(v, p) : p \in E^\alpha\} > 0$, thereby contradicting that the net ζ (Hausdorff) converges to E .

Next, suppose that there exists $\mu \in (\bigcap_\alpha E^\alpha) \setminus E$. Then, since E is closed, $\inf\{\varrho(\mu, v) : v \in E\} > 0$. Now, since ζ (Hausdorff) converges to E , there exists β such that the Hausdorff distance between E^β and E , call it h , is less than $\inf\{\varrho(\mu, v) : v \in E\}$. But $\mu \in E^\beta$ (since $\mu \in \bigcap_\alpha E^\alpha$), and therefore

$$\inf\{\varrho(\mu, v) : v \in E\} \leq \max_{p \in E^\beta} \sup_{v \in E} \varrho(p, v), \sup_{v \in E} \inf_{p \in E^\beta} \varrho(p, v) = h,$$

a contradiction.

Since $\bigcap_\alpha E^\alpha$ is a lower bound for (E^α) (and (E^α) was arbitrary), we conclude that every decreasing chain has a lower bound. Consequently, Zorn's lemma gives a minimal element E^* of \mathcal{E}_G ,

i.e., a stable set of G . Finally, it is easily seen that each element of E^* is a *thp* equilibrium of G . Hence, by Proposition 1 of Carbonell-Nicolau (forthcoming-a), the members of E^* are also Nash equilibria of G . \square

In light of Lemma 1, we seek conditions on the data of a game $G = (X_i, u_i)_{i=1}^N$ that ensure the existence of Nash equilibria in neighboring Selten perturbations of G .

Condition (B). For each i and every $\varepsilon > 0$, there is a sequence (f_k) of Borel measurable maps $f_k : X_i \rightarrow X_i$ such that the following is satisfied:

- (a) For each $(x_i, x_{-i}) \in X_i \times X_{-i}$ and each k , there is a neighborhood $O_{x_{-i}}$ of x_{-i} for which $u_i(f_k(x_i), y_{-i}) > u_i(x_i, x_{-i}) - \varepsilon$ for all $y_{-i} \in O_{x_{-i}}$.
- (b) For each $(x_i, x_{-i}) \in X_i \times X_{-i}$, there exists a real number $K_{(x_i, x_{-i})}$ such that for each $k \geq K_{(x_i, x_{-i})}$, there is a neighborhood $O_{x_{-i}}$ of x_{-i} such that $u_i(f_k(x_i), y_{-i}) < u_i(x_i, y_{-i}) + \varepsilon$ for all $y_{-i} \in O_{x_{-i}}$.

We omit the proof of the following lemma, which is an adaptation of the argument used in Carbonell-Nicolau (forthcoming-a) to prove Lemma 4. The details appear in Carbonell-Nicolau (2010b).

Lemma 2. Suppose that a compact, metric game G satisfies Condition (B). Then $\bar{G}_{\delta\mu}$ is payoff secure for every $(\delta, \mu) \in [0, 1) \times \hat{M}$.

We are now ready to state and prove the first main result.

Theorem 1. Suppose that $G = (X_i, u_i)_{i=1}^N$ is compact, metric, and satisfies Condition (B). Suppose further that $\sum_{i=1}^N u_i$ is upper semicontinuous. Then G has a stable set, and all stable sets of G contain only trembling-hand perfect equilibria, which are also Nash.

Proof. Suppose that $G = (X_i, u_i)_{i=1}^N$ is compact, metric, and satisfies Condition (B). Suppose further that $\sum_{i=1}^N u_i$ is upper semicontinuous. By Lemma 2, $\bar{G}_{\delta\mu}$ is payoff secure for every $(\delta, \mu) \in [0, 1) \times \hat{M}$. Further, since $\sum_{i=1}^N u_i$ is upper semicontinuous, so is $\sum_{i=1}^N U_i$. Consequently, by Proposition 3.2 in Reny (1999), $\bar{G}_{\delta\mu}$ is better-reply secure for every $(\delta, \mu) \in [0, 1) \times \hat{M}$, and hence by Corollary 3.3 in Reny (1999), $\bar{G}_{\delta\mu}$ possesses a Nash equilibrium for every $(\delta, \mu) \in (0, 1) \times \hat{M}$. Now apply Lemma 1. \square

Remark 1. Carbonell-Nicolau (forthcoming-a) proves the existence of *thp* equilibria in a superset of the set of compact, metric games satisfying Condition (B) and upper semicontinuity of the sum of payoffs. It can be shown that this superset contains games G for which the following is true: given any $\mu \in \hat{M}$ and $\delta \in (0, 1)^N$, there are many ρ arbitrarily close to μ such that $\bar{G}_{\delta\rho}$ fails payoff security and better-reply security. Consequently, proving that stable sets exist within the larger class considered in Carbonell-Nicolau (forthcoming-a) poses difficulties.

4. Generic games

This section provides conditions under which stable sets reduce to equilibrium points.

The following definition appears in Monteiro and Page (2007).

Definition 6. The game G is **uniformly payoff secure** if for each i , $\varepsilon > 0$, and $x_i \in X_i$, there exists $y_i \in X_i$ such that for every $x_{-i} \in X_{-i}$, there is a neighborhood $O_{x_{-i}}$ of x_{-i} such that $u_i(y_i, y_{-i}) > u_i(x_i, x_{-i}) - \varepsilon$ for all $y_{-i} \in O_{x_{-i}}$.

For fixed action spaces X_1, \dots, X_N , and letting $X := \times_i X_i$, consider the following classes of games:

- The class \mathfrak{g}_X^c of compact, metric games $(X_i, u_i)_{i=1}^N$ with u_i continuous for each i .
- The class \mathfrak{g}_X^u of compact, metric, and uniformly payoff secure games $(X_i, u_i)_{i=1}^N$ with $\sum_{i=1}^N u_i$ upper semicontinuous.
- The class \mathfrak{g}_X of compact, metric games $(X_i, u_i)_{i=1}^N$ satisfying Condition (B) and upper semicontinuity of $\sum_{i=1}^N u_i$.

It is clear that $\mathfrak{g}_X^c \subseteq \mathfrak{g}_X^u \supseteq \mathfrak{g}_X$. We view \mathfrak{g}_X^c , \mathfrak{g}_X^u , and \mathfrak{g}_X as metric subspaces of the metric space $(B(X)^N, \rho_X)$, where $B(X)$ represents the set of bounded maps $f : X \rightarrow \mathbb{R}$, with associated metric $\rho_X : B(X)^N \times B(X)^N \rightarrow \mathbb{R}$ defined by

$$\rho_X((u_1, \dots, u_N), (f_1, \dots, f_N)) := \sum_{i=1}^N \sup_{x \in X} |u_i(x) - f_i(x)|.$$

Definition 7. Given a class of games $\mathfrak{g} \subseteq B(X)^N$ and $G \in \mathfrak{g}$, a Nash equilibrium μ of \bar{G} is an **essential equilibrium of G relative to \mathfrak{g}** if for every neighborhood O_μ of μ there is a neighborhood O_G of G such that for every $g \in O_G \cap \mathfrak{g}$, O_μ contains a mixed-strategy Nash equilibrium of g .

Theorem 2 (Zhou et al., 2007, Theorem 1). For any G in a dense \mathfrak{g}_δ subset of \mathfrak{g}_X^c , any mixed-strategy Nash equilibrium of G is essential relative to \mathfrak{g}_X^c .

It is easy to show, using Theorem 2, that for generic elements G of \mathfrak{g}_X^c (i.e., for any G in a dense \mathfrak{g}_δ subset of \mathfrak{g}_X^c), any $\{\mu\}$ is stable for every mixed-strategy Nash equilibrium μ of G .

In fact, given $\delta \in [0, 1)^N$ and $\mu \in \hat{M}$, a carefully chosen perturbation of any G in \mathfrak{g}_X^c has a mixed extension that “coincides” with $\bar{G}_{\delta\mu}$. To see this, consider the mixed extension of the game

$$G_{(\delta, \mu)} = (X_i, u_i^{(\delta, \mu)})_{i=1}^N,$$

where $u_i^{(\delta, \mu)} : X \rightarrow \mathbb{R}$ is defined by

$$u_i^{(\delta, \mu)}(x) := U_i((1 - \delta_1)x_1 + \delta_1\mu_1, \dots, (1 - \delta_N)x_N + \delta_N\mu_N).$$

Here, $(1 - \delta_i)x_i + \delta_i\mu_i$ is a member of M_i defined by $((1 - \delta_i)x_i + \delta_i\mu_i)(B_i) := (1 - \delta_i)\delta_{x_i}(B_i) + \delta_i\mu_i(B_i)$, where δ_{x_i} denotes the Dirac measure on X_i with support $\{x_i\}$. Observe that given a Nash equilibrium $(\sigma_1, \dots, \sigma_N)$ in the mixed extension of $G_{(\delta, \mu)}$, $((1 - \delta_1)\sigma_1 + \delta_1\mu_1, \dots, (1 - \delta_N)\sigma_N + \delta_N\mu_N)$ is a Nash equilibrium of $\bar{G}_{\delta\mu}$. Moreover, $G_{(\delta, \mu)}$ is a perturbation of G in \mathfrak{g}_X^c . Consequently, by Theorem 2, for a generic game G (in \mathfrak{g}_X^c) any singleton set of mixed-strategy Nash equilibria is stable. In addition, by Theorem 1, all stable sets of G contain only *thp* equilibria, which are also Nash.

In light of the following extension of Theorem 2 to the superset \mathfrak{g}_X^u of \mathfrak{g}_X^c , it is natural to ask whether a similar result can be obtained for the class \mathfrak{g}_X^u .

Theorem 3 (Carbonell-Nicolau, 2010a, Corollary 1). For any G in a dense \mathfrak{g}_δ subset of \mathfrak{g}_X^u , any mixed-strategy Nash equilibrium of G is essential relative to \mathfrak{g}_X^u .

Unfortunately, given $G \in \mathfrak{g}_X^u \setminus \mathfrak{g}_X^c$, the perturbation $G_{(\delta, \mu)}$ need not lie in \mathfrak{g}_X^u (Carbonell-Nicolau, forthcoming-a, Example 3), so that even an essential game in \mathfrak{g}_X^u (i.e., a game whose mixed-strategy Nash equilibria are all essential) cannot be guaranteed to have stable singleton sets of mixed-strategy Nash equilibria via Theorem 3. Nevertheless, the genericity result extends to the class \mathfrak{g}_X . To see this, the following observations are essential (for their proofs, the reader is referred to Carbonell-Nicolau (2010b)).

Lemma 3. Suppose that G is a compact, metric game satisfying Condition (B). Then, for every $(\delta, \mu) \in [0, 1)^N \times \hat{M}$, $G_{(\delta, \mu)}$ is a compact, metric game satisfying Condition (B).

Lemma 4. Suppose that $\mathfrak{g} \subseteq \mathfrak{g}_X^u$ and \mathfrak{g} is closed in $B(X)^N$. Then, for any G in a dense \mathfrak{g}_δ subset of \mathfrak{g} , any mixed-strategy Nash equilibrium of G is essential relative to \mathfrak{g} .

Lemma 5. *The set \mathfrak{g}_X is closed in $B(X)^N$.*

Lemma 3 and upper semicontinuity of $\sum_{i=1}^N u_i$ imply that, given $G \in \mathfrak{g}_X$ and $(\delta, \mu) \in [0, 1)^N \times \widehat{M}$, we have $G_{(\delta, \mu)} \in \mathfrak{g}_X$ (upper semicontinuity of $\sum_{i=1}^N u_i^{(\delta, \mu)}$ is implied by that of $\sum_{i=1}^N U_i$, which, in turn, follows from upper semicontinuity of $\sum_{i=1}^N u_i$).

We are now ready to prove our second main result. Because $\mathfrak{g}_X \subseteq \mathfrak{g}_X^u$ is closed in $B(X)^N$ (**Lemma 5**), **Lemma 4** implies that for any G in a dense \mathfrak{g}_δ subset of \mathfrak{g}_X , any mixed-strategy Nash equilibrium of G is essential relative to \mathfrak{g}_X . Therefore, since, given $\delta \in [0, 1)^N$ and $\mu \in \widehat{M}$, $G_{(\delta, \mu)}$ is a perturbation of G in \mathfrak{g}_X , and because $((1 - \delta_1)\sigma_1 + \delta_1\mu_1, \dots, (1 - \delta_N)\sigma_N + \delta_N\mu_N)$ is a Nash equilibrium of $G_{(\delta, \mu)}$ whenever $(\sigma_1, \dots, \sigma_N)$ is a Nash equilibrium of the mixed extension of $G_{(\delta, \mu)}$, for a generic game G in \mathfrak{g}_X (i.e., for any G in a dense \mathfrak{g}_δ subset of \mathfrak{g}_X) any singleton set of mixed-strategy Nash equilibria is stable. In addition, by **Theorem 1**, all stable sets of G contain only *thp* equilibria, which are also Nash. Finally, it is easy to see that any stable set of G is a singleton set of mixed-strategy Nash equilibria.

Theorem 4. *For any G in a dense \mathfrak{g}_δ subset of \mathfrak{g}_X , a set is stable if and only if it contains a single mixed-strategy Nash equilibrium of G .*

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